

HW #5 Solutions

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$$1) \quad \underline{\dot{x}} = \begin{pmatrix} 3 & -2 \\ 2 & -2 \end{pmatrix} \underline{x}$$

$$\begin{vmatrix} 3-r & -2 \\ 2 & -2-r \end{vmatrix} = -(3-r)(2+r) + 4 =$$

$$= -6 - r + r^2 + 4 =$$

$$= r^2 - r - 2 = (r-2)(r+1)$$

$$r_1 = -1, \quad r_2 = 2$$

$$r_1 = -1: \quad \underline{z}^{(1)} = \begin{pmatrix} z_1^{(1)} \\ z_2^{(1)} \end{pmatrix}$$

$$4z_1^{(1)} - 2z_2^{(1)} = 0$$

$$z_2^{(1)} = 2z_1^{(1)}$$

$$\text{CHOOSE } z_1^{(1)} = 1 \Rightarrow z_2^{(1)} = 2$$

$$\underline{z}^{(1)} = \begin{pmatrix} 1 \\ 2 \end{pmatrix}$$

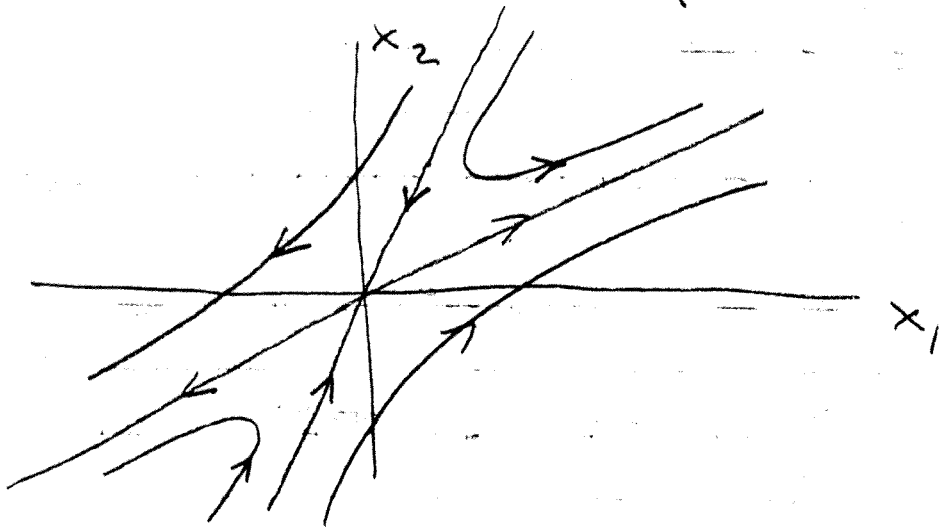
$$r_2 = 2: \quad \underline{z}^{(2)} = \begin{pmatrix} z_1^{(2)} \\ z_2^{(2)} \end{pmatrix}$$

$$z_1^{(2)} - 2z_2^{(2)} = 0$$

$$\text{CHOOSE } z_2^{(2)} = 1 \Rightarrow z_1^{(2)} = 2$$

$$\underline{z}^{(2)} = \begin{pmatrix} 2 \\ 1 \end{pmatrix}$$

$$\underline{x}(t) = c_1 \begin{pmatrix} 1 \\ 2 \end{pmatrix} e^{-t} + c_2 \begin{pmatrix} 2 \\ 1 \end{pmatrix} e^{2t}$$



2) $\dot{\underline{x}} = \begin{pmatrix} 1 & -2 \\ 3 & -4 \end{pmatrix} \underline{x}$

$$\begin{aligned} \begin{vmatrix} 1-r & -2 \\ 3 & -4-r \end{vmatrix} &= (1-r)(-4-r) + 6 = \\ &= -4 + 3r + r^2 + 6 = \\ &= r^2 + 3r + 2 = (r+2)(r+1) \end{aligned}$$

$$r_1 = -1, \quad r_2 = -2$$

$r_1 = -1$ $2z_1^{(1)} - 2z_2^{(1)} = 0$

CHOOSE $z_1^{(1)} = 1 \Rightarrow z_2^{(1)} = 1$

$$\underline{z}^{(1)} = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

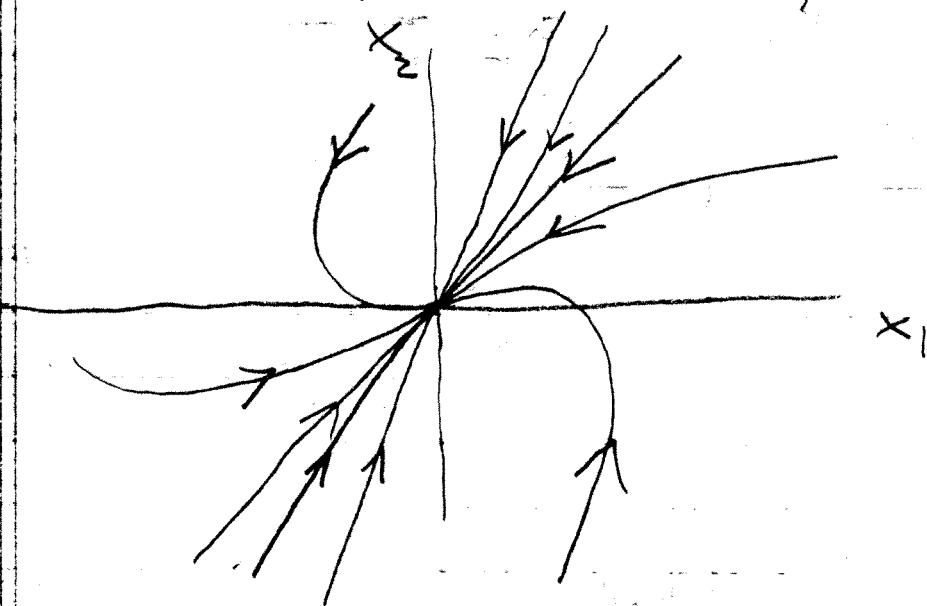
$$\underline{r_2 = -2}$$

$$3z_1^{(2)} - 2z_2^{(2)} = 0$$

$$\text{choose } z_1^{(2)} = 2 \Rightarrow z_2^{(2)} = 3$$

$$\underline{z}^{(2)} = \begin{pmatrix} 2 \\ 3 \end{pmatrix}$$

$$x(t) = c_1 \begin{pmatrix} 1 \\ 1 \end{pmatrix} e^{-t} + c_2 \begin{pmatrix} 2 \\ 3 \end{pmatrix} e^{-2t}$$



$$\# 3) \underline{\dot{x}} = \begin{pmatrix} 1 & 1 \\ 4 & -2 \end{pmatrix} x$$

$$\begin{aligned} \begin{vmatrix} 1-r & 1 \\ 4 & -2-r \end{vmatrix} &= (1-r)(-2-r) - 4 = \\ &= -2 + r + r^2 - 4 = \end{aligned}$$

$$= r^2 + r - 6 = (r-2)(r+3)$$

$$r_1 = 2, r_2 = -3$$

(2)

$$x_1 = z_1^{(1)} + z_2^{(1)} = 0$$

CHOOSE $z_1^{(1)} = 1 \Rightarrow z_2^{(1)} = -1$

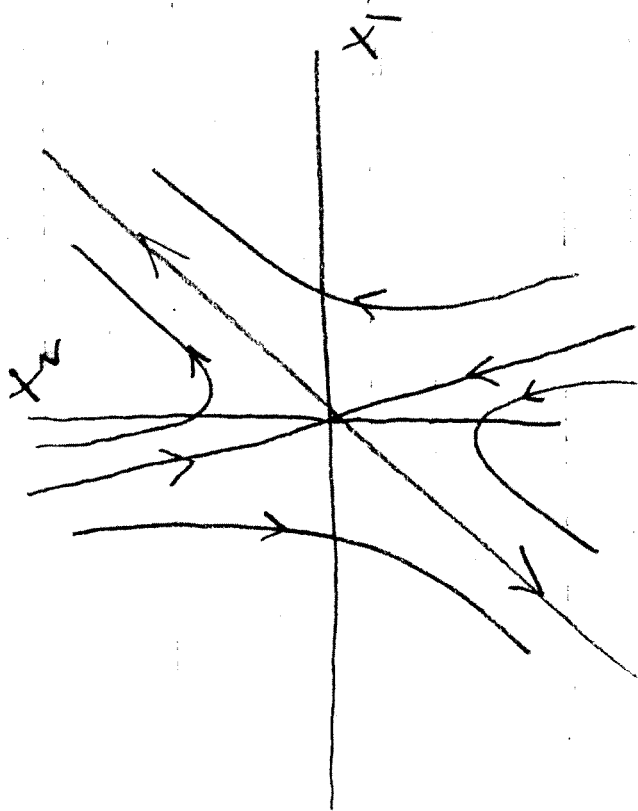
$$z^{(1)} = \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$

$x_2 = -z_1^{(2)} + z_2^{(2)} = 0$

CHOOSE $z_1^{(2)} = 1 \Rightarrow z_2^{(2)} = -1$

$$z^{(2)} = \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$

$$x = c_1 \begin{pmatrix} 1 \\ 1 \end{pmatrix} e^{2t} + c_2 \begin{pmatrix} 1 \\ -4 \end{pmatrix} e^{-3t}$$



#4)

3

$$x' = \begin{pmatrix} \frac{5}{4} & \frac{3}{4} \\ \frac{3}{4} & \frac{5}{4} \end{pmatrix} x$$

$$\begin{vmatrix} \frac{5}{4} - r & \frac{3}{4} \\ \frac{3}{4} & \frac{5}{4} - r \end{vmatrix} = \left(\frac{5}{4} - r\right)^2 - \frac{9}{16} = 0$$

$$= \frac{25}{16} - \frac{5}{2}r - \frac{9}{16} + r^2 = 0$$

$$= r^2 - \frac{5}{2}r + 1 = 0$$

$$= \left(r - \frac{1}{2}\right)(r - 2)$$

$$r_1 = \frac{1}{2}$$

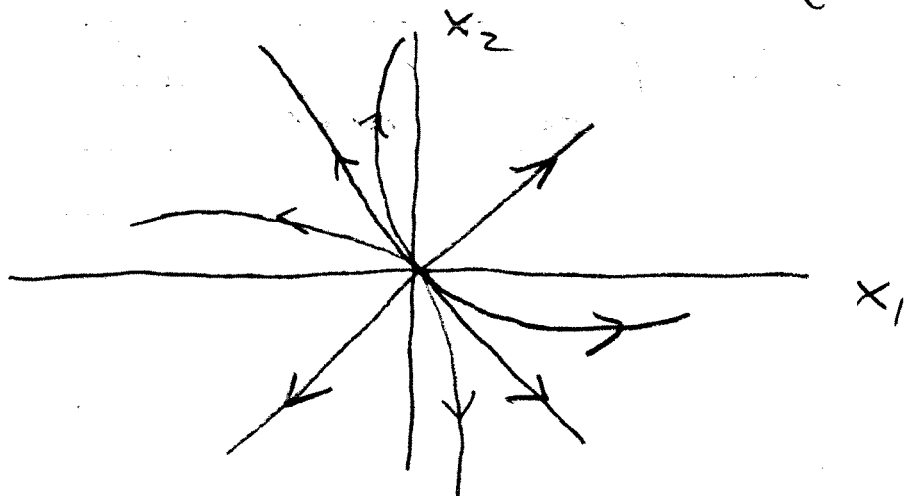
$$\frac{3}{4}z_1^{(1)} + \frac{3}{4}z_2^{(1)} = 0$$

$$\text{CHOOSE } z_1^{(1)} = 1 \Rightarrow z_2^{(1)} = -1 \quad \underline{z^{(1)}} = \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$

$$r_2 = 2: \quad -\frac{3}{4}z_1^{(2)} + \frac{3}{4}z_2^{(2)} = 0$$

$$\text{CHOOSE } z_1^{(2)} = 1 \Rightarrow z_2^{(2)} = 1 \quad \underline{z^{(2)}} = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$x(t) = c_1 \begin{pmatrix} 1 \\ -1 \end{pmatrix} e^{\frac{t}{2}} + c_2 \begin{pmatrix} 1 \\ 1 \end{pmatrix} e^{2t}$$



#5)

$$\dot{x} = \begin{pmatrix} 3 & -2 \\ 4 & -1 \end{pmatrix} x$$

$$\begin{vmatrix} 3-r & -2 \\ 4 & -1-r \end{vmatrix} = (3-r)(-1-r) + 4 = -3 - 2r + r^2 + 4 = r^2 - 2r + 1$$

$$r_1, r_2 = \frac{2 \pm \sqrt{4 - 4}}{2} = 1 \pm 2i$$

$$r_1 = 1 + 2i$$

$$(2 - 2i)z_1^{(1)} - 2z_2^{(1)} = 0$$

$$\text{choose: } z_1^{(1)} = 1 \Rightarrow z_2^{(1)} = 1 - i$$

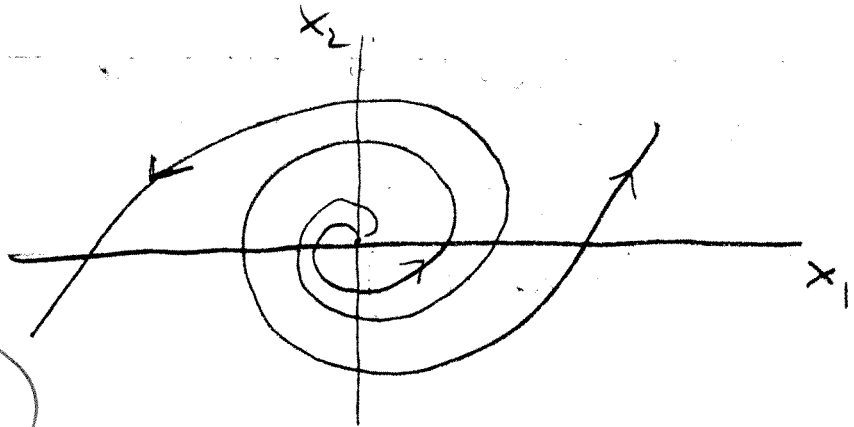
$$z^{(1)} = \begin{pmatrix} 1 \\ 1-i \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \end{pmatrix} + i \begin{pmatrix} 0 \\ -1 \end{pmatrix}$$

$$\begin{aligned} \underline{u}(t) &= e^{t} \left[\begin{pmatrix} 1 \\ 1 \end{pmatrix} \cos 2t - \begin{pmatrix} 0 \\ -1 \end{pmatrix} \sin 2t \right] = \\ &= e^{t} \begin{pmatrix} \cos 2t \\ \cos 2t + \sin 2t \end{pmatrix} \end{aligned}$$

$$\begin{aligned} \underline{v}(t) &= e^{t} \left[\begin{pmatrix} 1 \\ 1 \end{pmatrix} \sin 2t + \begin{pmatrix} 0 \\ -1 \end{pmatrix} \cos 2t \right] = \\ &= e^{t} \begin{pmatrix} \sin 2t \\ \sin 2t - \cos 2t \end{pmatrix} \end{aligned}$$

4

$$\underline{x}(t) = c_1 e^t \begin{pmatrix} \cos 2t \\ \sin 2t \end{pmatrix} + c_2 e^t \begin{pmatrix} \sin 2t \\ \cos 2t - \sin 2t \end{pmatrix}$$



#6)

$$\underline{\dot{x}} = \begin{pmatrix} -1 & -4 \\ 1 & -1 \end{pmatrix} \underline{x}$$

$$\begin{vmatrix} -1-r & -4 \\ 1 & -1-r \end{vmatrix} = (1+r)^2 + 4 = r^2 + 2r + 5$$

$$r_1, r_2 = \frac{-2 \pm \sqrt{4-20}}{2} = -1 \pm 2i$$

$$r_1 = -1 + 2i$$

$$-2i z_1^{(1)} - 4 z_2^{(1)} = 0$$

Choose $z_1^{(1)} = 2 \Rightarrow z_2^{(1)} = -1$

$$\underline{v}^{(1)} = \begin{pmatrix} 2 \\ 2 \\ -1 \end{pmatrix} = \begin{pmatrix} 2 \\ 0 \\ 0 \end{pmatrix} + \begin{pmatrix} 0 \\ 2 \\ -1 \end{pmatrix}$$

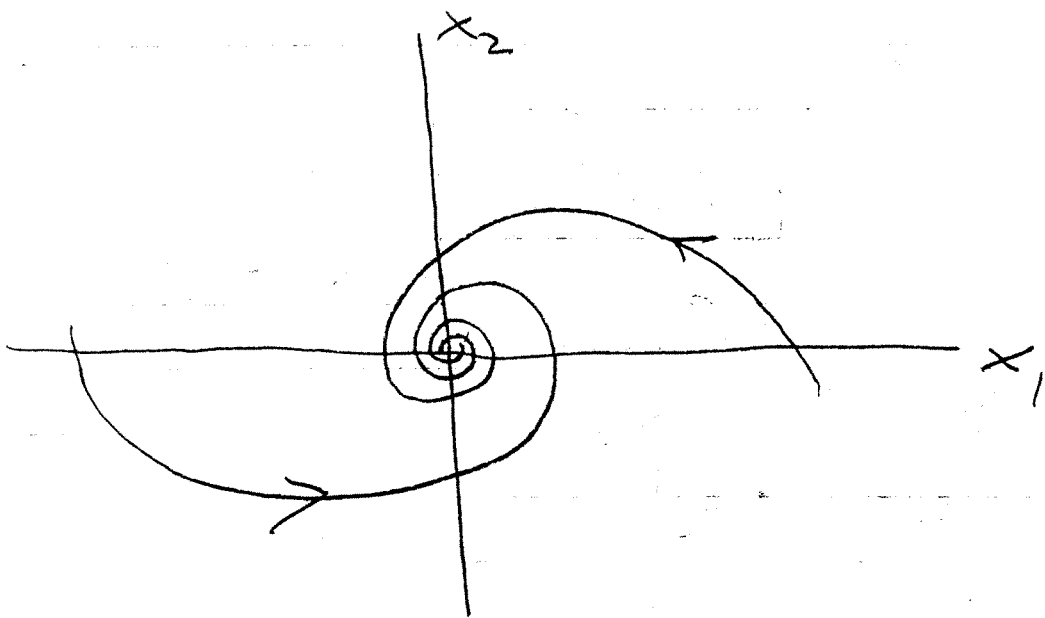
$$u(t) = e^{-t} \left[\begin{pmatrix} 2 \\ 0 \end{pmatrix} \cos 2t - \begin{pmatrix} 0 \\ -1 \end{pmatrix} \sin 2t \right] =$$

$$= e^{-t} \begin{pmatrix} 2 \cos 2t \\ \sin 2t \end{pmatrix}$$

$$v(t) = e^{-t} \left[\begin{pmatrix} 2 \\ 0 \end{pmatrix} \sin 2t + \begin{pmatrix} 0 \\ -1 \end{pmatrix} \cos 2t \right] =$$

$$= e^{-t} \begin{pmatrix} 2 \sin 2t \\ -\cos 2t \end{pmatrix}$$

$$x(t) = c_1 e^{-t} \begin{pmatrix} 2 \cos 2t \\ \sin 2t \end{pmatrix} + c_2 e^{-t} \begin{pmatrix} 2 \sin 2t \\ -\cos 2t \end{pmatrix}$$



#7)

$$\dot{x} = \begin{pmatrix} 2 & -5 \\ 1 & -2 \end{pmatrix} x$$

(5)

$$\begin{array}{cc|c} 2-r & -5 & \\ 1 & -2-r & \end{array} = (2-r)(-2-r) + 5 =$$

$$= -4 + r^2 + 5 = r^2 + 1 = 0$$

$$r_1 = i, \quad r_2 = -i$$

$$r_1 = i: (2-i)z_1^{(1)} - 5z_2^{(1)} = 0$$

choose: $z_1^{(1)} = 5, \quad z_2^{(1)} = (2-i)$

$$\underline{z}^{(1)} = \begin{pmatrix} 5 \\ 2-i \end{pmatrix} = \begin{pmatrix} 5 \\ 2 \end{pmatrix} + i \begin{pmatrix} 0 \\ -1 \end{pmatrix}$$

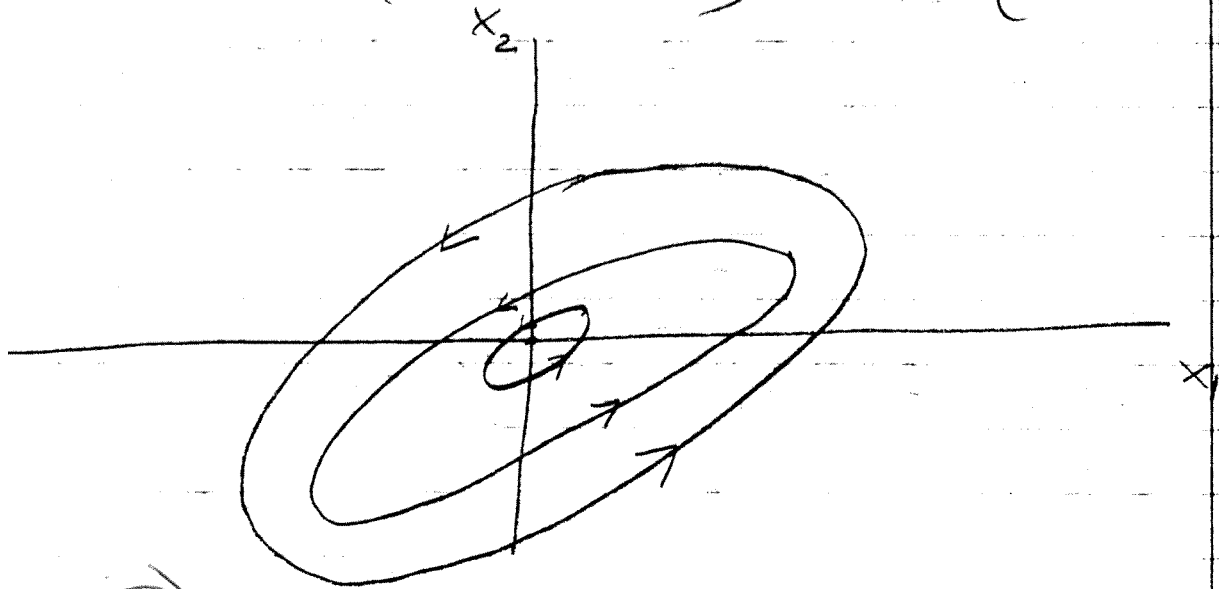
$$\underline{u}(t) = \begin{pmatrix} 5 \\ 2 \end{pmatrix} e^{it} - \begin{pmatrix} 0 \\ -1 \end{pmatrix} e^{it} =$$

$$= \begin{pmatrix} 5e^{it} \\ 2e^{it} + e^{it} \end{pmatrix}$$

$$\underline{v}(t) = \begin{pmatrix} 5 \\ 2 \end{pmatrix} e^{-it} + \begin{pmatrix} 0 \\ -1 \end{pmatrix} e^{-it} =$$

$$= \begin{pmatrix} 5e^{-it} \\ 2e^{-it} - e^{-it} \end{pmatrix}$$

$$\underline{x}(t) = c_1 \begin{pmatrix} 5 \cos t \\ 2 \cos t + \sin t \end{pmatrix} + c_2 \begin{pmatrix} 5 \sin t \\ 2 \sin t - \cos t \end{pmatrix}$$



#8)

$$\dot{\underline{x}} = \begin{pmatrix} 1 & 2 \\ -5 & -1 \end{pmatrix} \underline{x}$$

$$\begin{vmatrix} 1-r & 2 \\ -5 & -1-r \end{vmatrix} = (1-r)(-1-r) + 10 =$$

$$= -1 + r^2 + 10 = r^2 + 9 = 0$$

$$r_1 = 3i, \quad r_2 = -3i$$

$$\underline{r}_1 = 3i: \quad (1+3i)z_1^{(1)} + 2z_2^{(1)} = 0$$

$$\text{offset } z_1^{(1)} = -2 \Rightarrow z_2 = (1-3i)$$

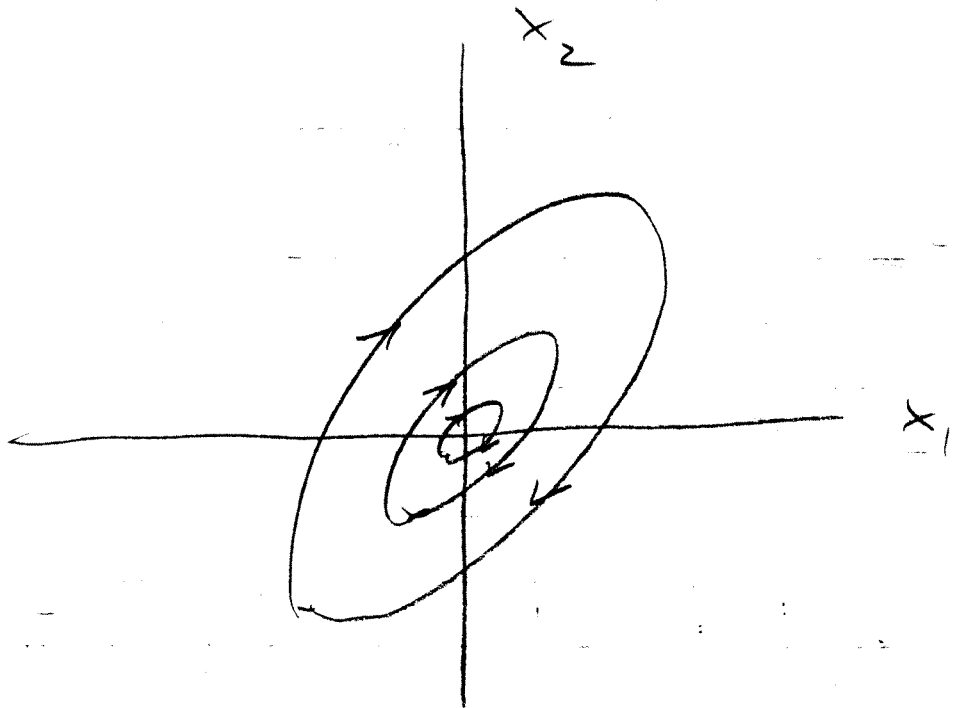
$$z^{(1)} = \begin{pmatrix} -2 \\ 1-3i \end{pmatrix} = \begin{pmatrix} -2 \\ 1 \end{pmatrix} + i \begin{pmatrix} 0 \\ -3 \end{pmatrix}$$

(6)

$$\begin{aligned} \underline{u}(t) &= \begin{pmatrix} -2 \\ 1 \end{pmatrix} \cos 3t - \begin{pmatrix} 0 \\ -3 \end{pmatrix} \sin 3t \\ &= \begin{pmatrix} -2 \cos 3t \\ \cos 3t + 3 \sin 3t \end{pmatrix} \end{aligned}$$

$$\begin{aligned} \underline{v}(t) &= \begin{pmatrix} -2 \\ 1 \end{pmatrix} \sin 3t + \begin{pmatrix} 0 \\ -3 \end{pmatrix} \cos 3t \\ &= \begin{pmatrix} -2 \sin 3t \\ \sin 3t - 3 \cos 3t \end{pmatrix} \end{aligned}$$

$$\underline{x}(t) = c_1 \begin{pmatrix} -2 \cos 3t \\ \cos 3t + 3 \sin 3t \end{pmatrix} + c_2 \begin{pmatrix} -2 \sin 3t \\ \sin 3t - 3 \cos 3t \end{pmatrix}$$



#9)

$$\underline{\dot{x}} = \begin{pmatrix} 1 & \sqrt{3} \\ \sqrt{3} & -1 \end{pmatrix} x$$

$$\underline{\dot{x}} = \begin{pmatrix} 1 & \sqrt{3} \\ \sqrt{3} & -1 \end{pmatrix} x$$

$$\begin{vmatrix} 1-r & \sqrt{3} \\ \sqrt{3} & -1-r \end{vmatrix} = (1-r)(-1-r) - 3 = \\ = -1 + r^2 - 3 = r^2 - 4 = \\ = (r-2)(r+2)$$

$$\underline{r_1 = 2} \quad -z_1^{(1)} + \sqrt{3} z_2^{(1)} = 0$$

$$\underline{z_2^{(1)} = 1} \Rightarrow z_1^{(1)} = \sqrt{3}$$

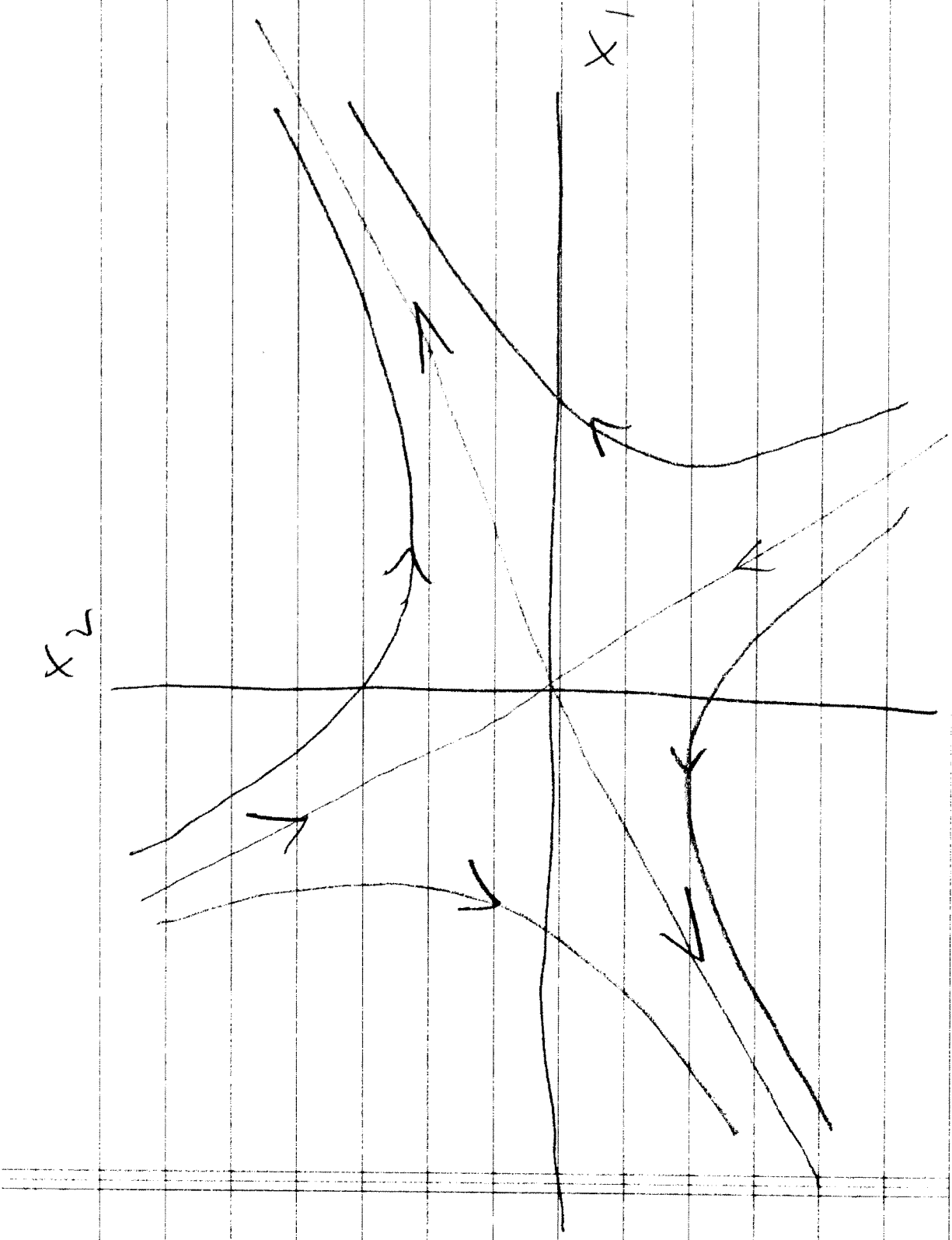
$$\underline{z^{(1)}} = \begin{pmatrix} \sqrt{3} \\ 1 \end{pmatrix}$$

$$\underline{r_2 = -2} \quad 3z_1^{(2)} + \sqrt{3} z_2^{(2)} = 0$$

$$z_1^{(2)} = 1, \quad z_2^{(2)} = -\sqrt{3}$$

$$\underline{z^{(2)}} = \begin{pmatrix} 1 \\ -\sqrt{3} \end{pmatrix}$$

$$\underline{x(t)} = c_1 \begin{pmatrix} \sqrt{3} \\ 1 \end{pmatrix} e^{2t} + c_2 \begin{pmatrix} 1 \\ -\sqrt{3} \end{pmatrix} e^{-2t}$$



$$10) \dot{X} = \overset{A}{\begin{pmatrix} 3 & -4 \\ 1 & -1 \end{pmatrix}}$$

$$\det \begin{pmatrix} 3-r & -4 \\ 1 & -1-r \end{pmatrix}$$

$$= (3-r)(-1-r) + 4$$

$$= -3 + 2r + r^2 + 4$$

$$= r^2 - 2r + 1 = (r-1)^2 = 0$$

$$\Rightarrow r = 1$$

$$(A - rI)z = \begin{pmatrix} 2 & -4 \\ 1 & -2 \end{pmatrix} \begin{pmatrix} z_1 \\ z_2 \end{pmatrix} = 0$$

$$\Rightarrow z_1 = +2z_2 \Rightarrow z = \begin{pmatrix} +2 \\ 1 \end{pmatrix}$$

set $z_2 = 1$

Need another eigenvector (generalized)

$$(A - rI)\eta = z$$

$$\Rightarrow \begin{pmatrix} 2 & -4 \\ 1 & -2 \end{pmatrix} \begin{pmatrix} \eta_1 \\ -\eta_2 \end{pmatrix} = \begin{pmatrix} +2 \\ 1 \end{pmatrix}$$

$$\Rightarrow \eta_1 - 2\eta_2 = 1$$

$$\Rightarrow \eta_1 = 1 + 2\eta_2$$

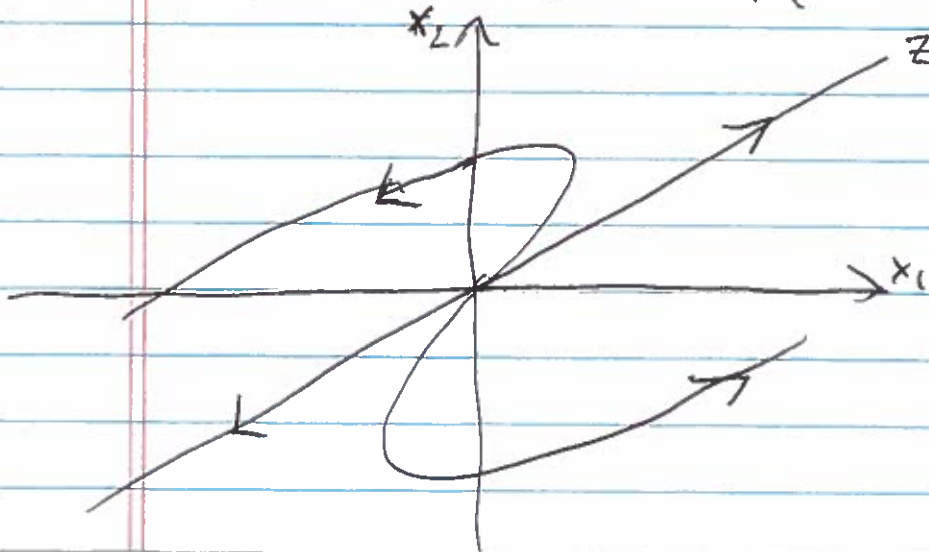
$$\Rightarrow \eta = \begin{pmatrix} 1 + 2\eta_2 \\ \eta_2 \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \end{pmatrix} + \eta_2 \begin{pmatrix} 2 \\ 1 \end{pmatrix}$$

$\underbrace{\begin{pmatrix} 2 \\ 1 \end{pmatrix}}_{=z}$
 part of first
 eigenvector

$$\Rightarrow \eta_2 = 0$$

solution

$$X = C_1 z e^t + C_2 (z t e^t + \eta e^t)$$



$$A \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \begin{pmatrix} -4 \\ -1 \end{pmatrix}$$

\uparrow test
 direction of flow

$$11) \quad \dot{x} = Ax = \begin{pmatrix} -3 & 5/2 \\ -5/2 & 2 \end{pmatrix} x$$

$$\det \begin{pmatrix} -3 - r & 5/2 \\ -5/2 & 2 - r \end{pmatrix}$$

$$= r^2 + r - 6 + \frac{25}{4}$$

$$= r^2 + r + \frac{1}{4} = \left(r + \frac{1}{2}\right)^2 = 0$$

$$\Rightarrow r = -1/2$$

$$(A - rI)z = \begin{pmatrix} -5/2 & 5/2 \\ -5/2 & 5/2 \end{pmatrix} \begin{pmatrix} z_1 \\ z_2 \end{pmatrix} = 0$$

$$\Rightarrow z_1 = z_2 \Rightarrow z = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$\text{let } z_1 = 1$$

$$(A - rI)\eta = z$$

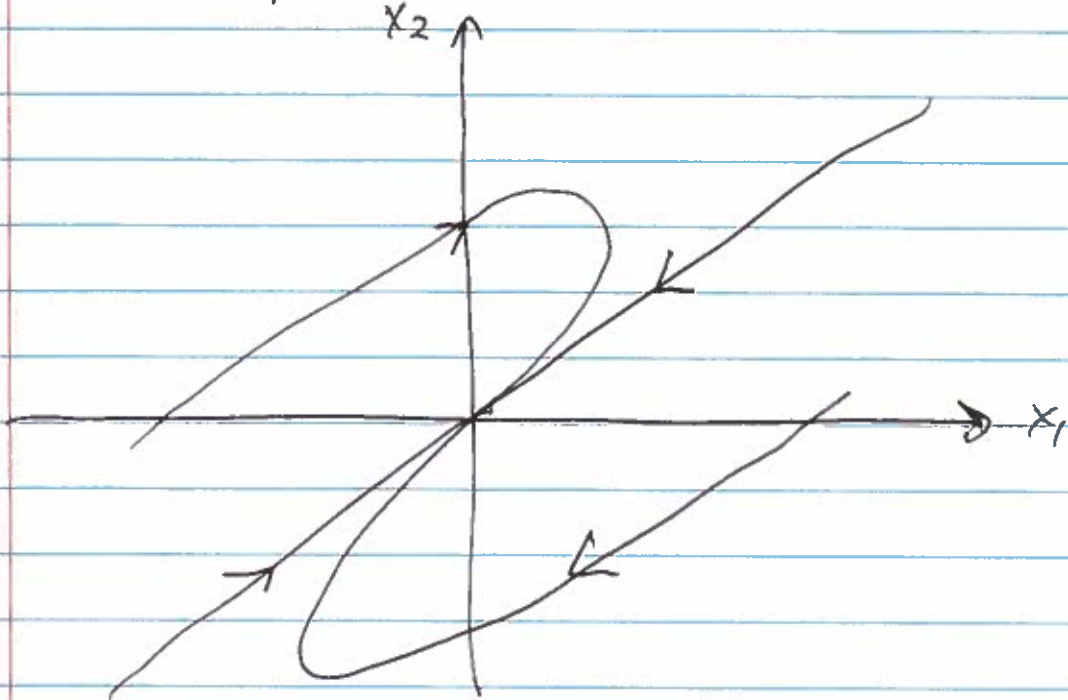
$$\Rightarrow \begin{pmatrix} -5/2 & 5/2 \\ -5/2 & 5/2 \end{pmatrix} \begin{pmatrix} \eta_1 \\ \eta_2 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

part of let
 $z \Rightarrow \eta_1 = 0$
 \downarrow

$$\Rightarrow 5\eta_2 = 2 + 5\eta_1 \Rightarrow \eta = \begin{pmatrix} 0 \\ 2/5 \end{pmatrix} + \eta_1 \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$\Rightarrow \eta_2 = \frac{2}{5} + \eta_1$$

$$X = c_1 z e^{-t/2} + c_2 (z t e^{-t/2} + \eta e^{-t/2})$$



Direction of
trajectories
at points:

$$A \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 5/2 \\ 5/2 \end{pmatrix} = \begin{pmatrix} 5/2 \\ 2 \end{pmatrix} = \nearrow$$

$$A \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \begin{pmatrix} -3 \\ -5/2 \end{pmatrix} = \swarrow$$

$$(2) \quad \dot{x} = Ax = \begin{pmatrix} -3/2 & 1 \\ -1/4 & -1/2 \end{pmatrix} x$$

$$\det(A - rI) = \det \begin{pmatrix} -3/2 - r & 1 \\ -1/4 & -1/2 - r \end{pmatrix}$$

$$= r^2 + 2r + 3/4 + 1/4 = r^2 + 2r + 1$$

$$= (r+1)^2 = 0 \Rightarrow r = -1$$

$$(A - rI)z = \begin{pmatrix} -1/2 & 1 \\ -1/4 & 1/2 \end{pmatrix} \begin{pmatrix} z_1 \\ z_2 \end{pmatrix} = 0$$

$$\Rightarrow z_1 = 2z_2 \Rightarrow z = \begin{pmatrix} 2 \\ 1 \end{pmatrix}$$

let $z_2 = 1$

$$(A - rI)\eta = z$$

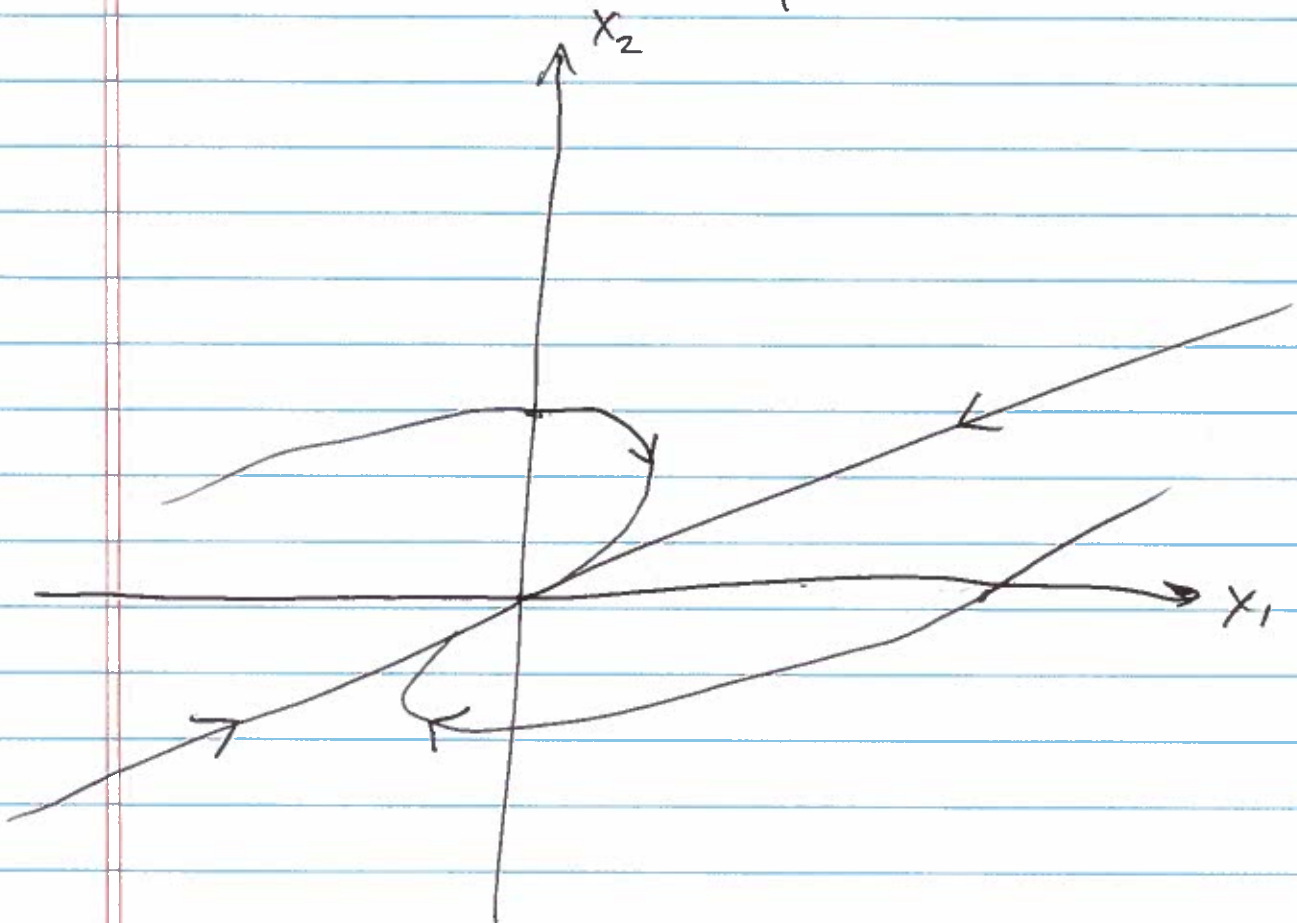
$$\Rightarrow \begin{pmatrix} -1/2 & 1 \\ -1/4 & 1/2 \end{pmatrix} \begin{pmatrix} \eta_1 \\ \eta_2 \end{pmatrix} = \begin{pmatrix} 2 \\ 1 \end{pmatrix}$$

$$\eta_2 = 2 + 1/2 \eta_1$$

$$\rightarrow \eta = \begin{pmatrix} 0 \\ 2 \end{pmatrix} + \frac{\eta_1}{2} \begin{pmatrix} 2 \\ 1 \end{pmatrix}$$

part of
 z
already

$$x = c_1 z e^{-t} + c_2 (z t e^{-t} + \eta e^{-t})$$



Direction of
trajectories
at points:

~~At (0,1)~~

$$\dot{x} = A \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 1 \\ -1/2 \end{pmatrix} = \searrow$$

$$\dot{x} = A \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \begin{pmatrix} -3/2 \\ -1/4 \end{pmatrix} = \swarrow$$